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MCMC in pratice

Markov chain convergence

In Bayesian analysis, MCMC algorithms are used to obtain a **Monte Carlo sample** from the *posterior* distribution

⇒ requires **Markov chain convergence** towards its stationary law (*posterior* distribution).

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Convergence diagnostics

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⇒ study the convergence empirically for each analysis

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⇒ requires **Markov chain convergence** towards its stationary law (*posterior* distribution).

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⇒ study the convergence empirically for each analysis

♀ Initialisation of several Markov chains from different initial values
⇒ If convergence is reached, then these chains must be overlapping

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Convergence diagnostics

Graphical diagnostics

- Trace
- Posterior density
- Running Quantiles
- Gelman-Rubin diagram
- Auto-correlogram

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Trace

coda::traceplot()



chain traces must overlap and mix
/ n.iter and/or / burn-in



coda::densplot()



density must be smooth and uni-modal
/ n.iter and/or / burn-in

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Convergence diagnostics

Running quantiles

coda::cumuplot()



😁 running quantiles must be stable across iterations

Gelman-Rubin statistic

- · variation between the different chains
- variation within a given chain

If the algorithm has properly converged, the between-chain variation must be close to zero

 $\theta_{[c]} = (\theta_{[c]}^{(1)}, \dots, \theta_{[c]}^{(N)})$ the *N*-sample from chain number $c = 1, \dots, C$ Gelman-Rubin statistic: $R = \frac{\frac{N-1}{N}W\frac{1}{N}B}{W}$

- between-chain variance: $B = \frac{N}{C-1} \sum_{c=1}^{C} (\bar{\theta}_{[C]} \bar{\theta}_{.})^2$
- chain average: $\bar{\theta}_{[c]} = \frac{1}{N} \sum_{t=1}^{N} \theta_{[c]}^{(t)}$
- global average: $\bar{\theta}_{\cdot} = \frac{1}{C} \sum_{c=1}^{C} \bar{\theta}_{[C]}$
- within-chain variance: $s_{[c]}^2 = \frac{1}{N-1} \sum_{t=1}^{N} (\theta_{[c]}^{(t)} \bar{\theta}_{[C]})^2$

$$N \to +\infty \& B \to 0 \Rightarrow R \to 1$$

Other statistics exist. . .

(C) B. Hejblum

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Convergence diagnostics

Gelman-Rubin diagram

coda::gelman.plot()



Gelman-Rubin statistic median must remain under the 1,01 threshold (or 1,05)
/ n.iter and/or / burn-in

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Effective Sample Size (ESS)

Markov property \Rightarrow **auto-correlation** between values sampled after one another (dependent sampling) :

- reduce the amount of information available within a sample size n
- slows down LLN convergence

Effective sample size quantifies this:

$$ESS = \frac{N}{1 + 2\sum_{k=1}^{+\infty} \rho(k)}$$

where $\rho(k)$ is the auto-correlation with lag k.

Space out saved samples (e.g. every 2, 5, or 10 iterations)

 \Rightarrow reduces dependency within the Monte Carlo sample generated

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coda::acfplot()



auto-correlations must decrease rapidly to oscillate around zero
/ thin and/or / n.iter and/or / burn-in

Monte Carlo error

For a given parameter, quantifies the error introduced through the Monte Carlo method

(standard deviation of the Monte Carlo estimator across the chains)

- That error must be consistent from one chain to another
- The larger N (number of iterations), the smaller the Monte Carlo error will be

 \triangle This **Monte Carlo error** must be small with respect to the estimated variance of the *posterior* distribution